

Mike11



WATEREUROPE

Hydroinformatics for water resources and water related hazards management in Europe



Erasmus+



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Hydraulic Modelling

1D River Modelling with Mike11



Introduction Mike11

Overview

Software Tools for 1D River Modelling

- examples for numerical simulation tools

1D Hydrodynamic Simulation

- assumptions
- river modelling elements

Theoretical Background

- unsteady flow, Saint-Venant equations
- numerical method Abbott-Ionesco scheme

Mike 11 Product

- components
- exercise: simple academic test case, simplified river model

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Part 1

Software Tools

1D River Modelling

Examples

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1D River Modelling Software Tools

Numerical Simulation Tools

- physics: based on the Saint-Venant Equations
- numerics: mainly Finite Difference Method
- examples

Mike11	DHI (DK)	-> MIKE HYDRO River
HEC-RAS	U.S. Army Corps of Engineers (USACE) Hydrologic Engineering Center (HEC)	
ISIS1D	Halcrow/CH2M/Jacobs(UK)	-> FloodModeller
SOBEK	Deltares (NL)	
Kalypso1D	TU Hamburg-Harburg Björnsen Consulting Engineers (D)	

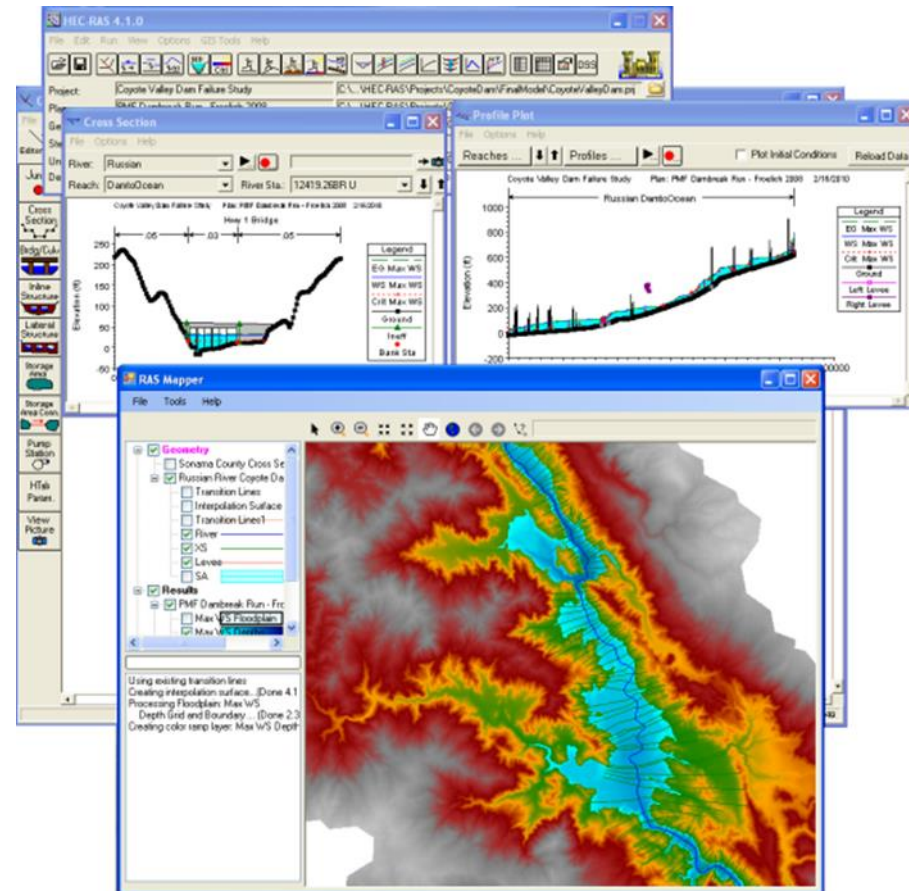


1D River Modelling Software Tools

HEC-RAS

Overview

- numerical simulation of 1D hydraulic water flow in natural and artificial channels subcritical, supercritical, mixed flow regime, bridges, culverts, weirs and structures
- simulation of:
 - steady flow
 - unsteady flow
 - sediment transport
 - mobile bed computations
 - water quality





1D River Modelling Software Tools

HEC-RAS

Overview

- provider: U.S. Army Corps of Engineers
Hydrologic Engineering Center
- license: public release (see web page for details) since 1995
- version: 5.0.6 (2018)
- approach: unsteady flow: 1D Saint-Venant equations
finite difference method
Preissmann implicit scheme or 4-point Box scheme
- Web page: <http://www.hec.usace.army.mil/software/hecras/>

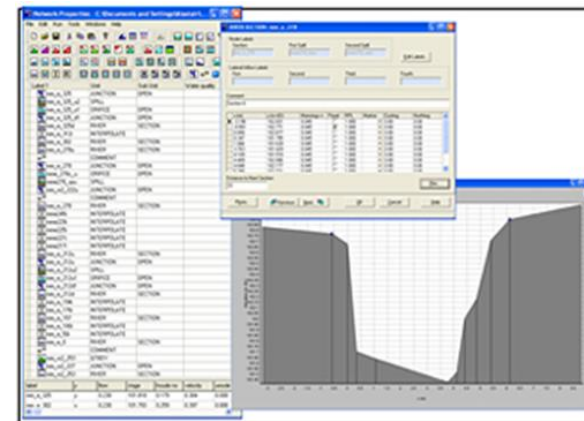
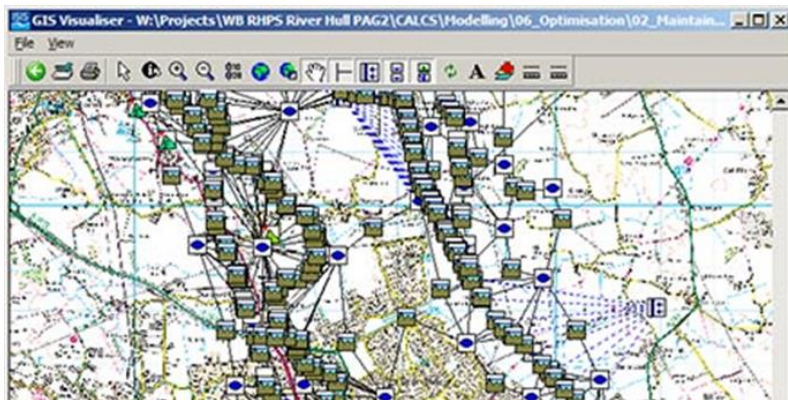


1D River Modelling Software Tools

ISIS1D

Overview

- full hydrodynamic simulator for flows and levels in open channels and estuaries, complex looped and branched networks
- complex structures and operating rules
- unsteady, steady, subcritical, supercritical and transitional flows
- water quality and sediment transport modules





1D River Modelling Software Tools

ISIS1D -> Flood Modeller Suite

Overview

- provider: Jacobs / CH2M / Halcrow (UK)
- license: ISISFree and ISIS1D (see web page for details)
- approach: unsteady flow: 1D Saint-Venant equations
finite difference method
Preissmann implicit scheme or 4-point Box scheme
- Web page: <https://www.floodmodeller.com>
integration in **Flood Modeller Suite**

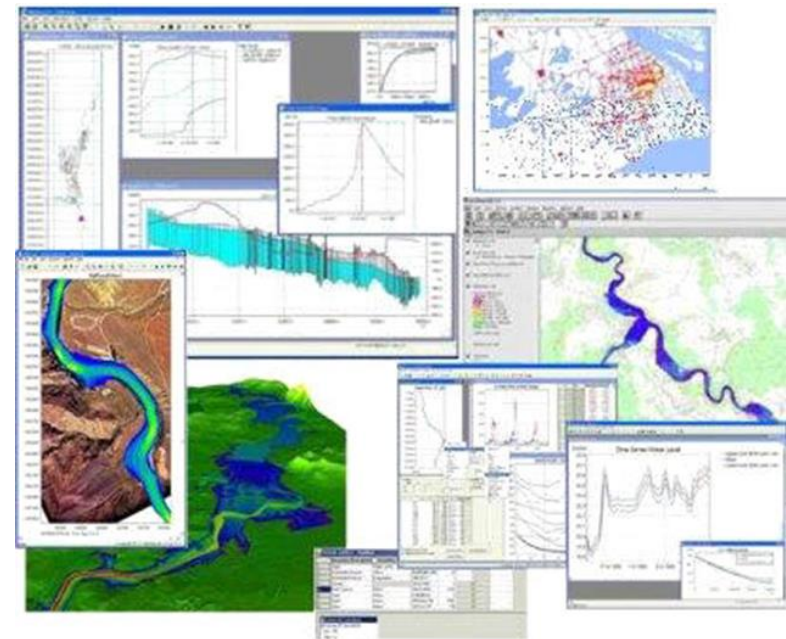


1D River Modelling Software Tools

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Overview

- steady and unsteady flow in branched and looped channel networks, and flood plains
- flow through a variety of structures
- subcritical and supercritical flow
- additional modules:
 - advection-dispersion
 - water quality and ecology
 - sediment transport
 - rainfall-runoff
 - flood forecasting
 - real-time operations
 - dam break





1D River Modelling Software Tools

MIKE11-> MIKE HYDRO River

Overview

- provider: DHI (DK)
- license: commercial and DEMO mode
- approach: unsteady flow: 1D Saint-Venant equations
finite difference method
Abbott-Ionescu implicit scheme (6-points)
- Web page: <http://www.mikepoweredbydhi.com>
Mike11 succeeded in the Mike2016 edition by:
MIKE HYDRO River



1D River Modelling Software Tools

Conclusion

- several similar tools available
commercial, freeware, open source
 - similar functionality
 - same theoretical background
e.g. Saint -Venant Equations
 - similar numerical approaches
e.g. implicit FDM scheme
- > software is no problem
- key factor of success
 - data availability
 - knowledge and expertise of the user!



Part 2

1D River Modelling

by

1D Hydrodynamic Numerical Simulation

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1D River Modelling

Approach

- reduction of the real-world flow processes to a 1D problem

Basic Assumptions

- water is incompressible and homogeneous
no significant variations in density
- the bottom slope is small
 $\sin(\alpha) = \alpha$ and $\cos(\alpha) = 1$
- wave lengths are large compared to the water depth
flow everywhere can be regarded as having a direction parallel to the bottom
vertical acceleration can be neglected
hydro-static pressure variation along the vertical can be assumed
- horizontal water level and equal velocity in a cross-section



1D River Modelling

River Var Flood Modelling

- What do we need ?
 - steady or unsteady flow ?
 - subcritical or supercritical flow ?
 - sediment transport, morphodynamics ?
 - water quality ?
- Which physical state variables we are looking for ?
- Which coordinates (space/time) are relevant ?



1D River Modelling

Steady and Unsteady Flow

- steady -> all the time derivatives of a flow field vanish

$$\frac{\partial Q}{\partial t} = 0 \quad \frac{\partial h}{\partial t} = 0$$

- unsteady (transient) -> some time derivatives $\neq 0$

$$\frac{\partial Q}{\partial t} \neq 0 \quad \frac{\partial h}{\partial t} \neq 0$$

examples for time derivatives



1D River Modelling

Var Flood Modelling - Assumptions

- unsteady flow
- subcritical flow
- supercritical flow nearby structures only
- no morphodynamics (assumption!)
- no water quality study and or impact to HD
- physical state variables: water level and discharge
- coordinates: 1D along the river and time
2D cross-section vertical to river: value integration / average



1D River Modelling

River Model Information Components

- geometry river location by points (geospatial location)
cross section vertical to river branches
- topology connection of branches -> channel network
- physics parameter for physical descriptions
of phenomena's such as gravitation, friction, ...
- structures description of different hydraulics structures,
e.g. weir, culverts, bridges, pumps, ...
- boundary cond. physical state variables at spatial model boundary
- initial condition physical state variables at begin of simulation period
- simulation period, time step, spatial approximation,
numerical parameter, stability criteria



1D River Modelling

Geometry and Topology Data

- list of points in a 2D earth surface coordinate reference system
-> global 2D geospatial coordinates
- connection of points to a line as river branch
-> local 1D coordinate along river -> chainage
- upstream/downstream connections -> river network
-> topological network structure
- cross section -> cut vertical to local 1D river longitudinal axis
-> 2D: local horizontal coordinate, global vertical coordinate
- structures: bridge, culvert, weir, pump stations, ...
-> location by 1D river coordinate (chainage)
-> relevant geometry of structure



1D River Modelling

Physics – Bed Resistance

- friction between river bed and water flow due to gravity in channels
- depends on bed type and slope
 - > less friction for smooth concrete
 - > typical friction for normal gravel
 - > high friction for rough stones/rocks and vegetation
- part of Saint-Venant equation
 - head loss (potential energy) due to friction along a channel



1D River Modelling

Physics – Bed Resistance

- Gauckler–Manning–Strickler formula (empiric)

$$v = \frac{1}{n} R_h^{2/3} S^{1/2}$$

v cross-sectional average velocity

n Manning coefficient

R_h hydraulic radius (-> wetted area / wetted perimeter)

S slope of the hydraulic grade line, channel bed slope (constant water depth)

- coefficients

Chezy coefficient $C = 1/n R^{1/6}$

Manning coefficient n

Strickler coefficient $K_s = 1/n$ (-> in Mike11 called Manning value M)

- mathematical relation between values
- North American / UK and European point of view



1D River Modelling

Physics – Bed Resistance

- Manning values - examples

Minor Streams (top width at flood stage < 30 m)

Streams on Plain	Manning n	Strickler K_s
1. Clean, straight, full stage, no rifts or deep pools	0.025–0.033	30-40
2. Same as above, but more stones and weeds	0.030–0.040	25-33
3. Clean, winding, some pools and shoals	0.033–0.045	22-30
4. Same as above, but some weeds and stones	0.035–0.050	20-29
5. Same as above, lower stages, more ineffective slopes and sections	0.040–0.055	18-25
6. Same as 4, but more stones	0.045–0.060	17-22
7. Sluggish reaches, weedy, deep pools	0.050–0.080	12-20
8. Very weedy reaches, deep pools, or floodways with heavy stand of timber and underbrush	0.075–0.150	07-13



1D River Modelling

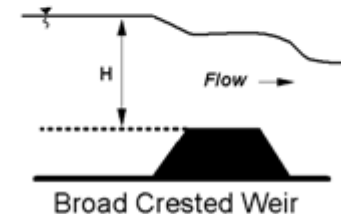
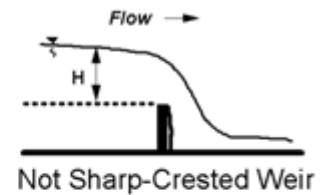
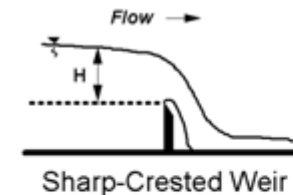
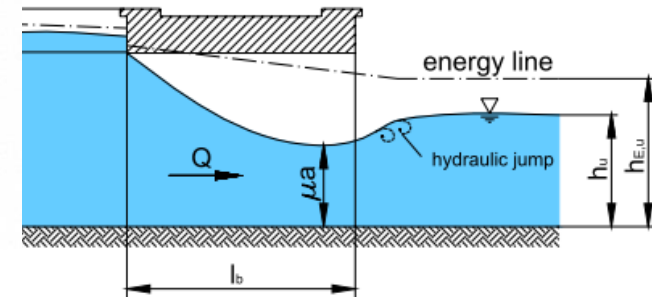
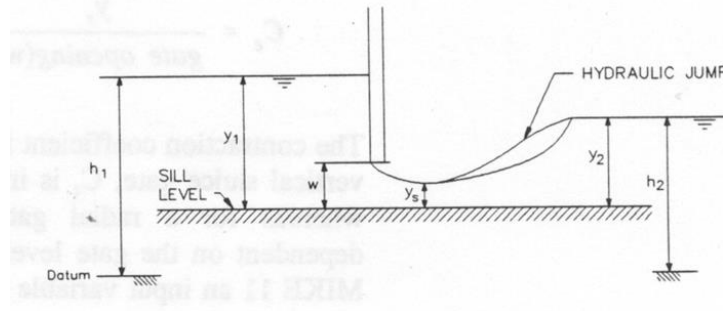
Structures

- weirs
- culverts
- control structures
- bridges
- pumps
- dams

integration of empirical equations
in the numerical scheme

-> Q/h relationships, empiric parameters

example weir -> Poleni equation $Q = \frac{2}{3} \mu \sqrt{2g} B h^{\frac{3}{2}}$





1D River Modelling

Boundary Conditions

- location: at the border / boundary of model
- time: at any time within the simulation period
- types of boundary conditions:
 - > 1st type Dirichlet -> water level is given
 - > 2nd type Neumann -> discharge is given
 - > 3rd type Cauchy -> Q/h relationship: rating curve
water level depending discharge
- values for boundary conditions
 - > constant values
 - > time series
- additional application: external sources as lateral inflow



1D River Modelling

Boundary Conditions for Rivers

- typical examples for upstream boundaries
 - > constant discharge from a reservoir
 - > discharge hydrograph for a specific event
- typical examples for downstream boundaries
 - > constant water level, e.g. in a large receiving water body
 - > time series of water level, e.g. tidal cycle
 - > rating curve (Q/h), e.g. from a gauging station
- What do we need for lower part of the river Var ?



1D River Modelling

Initial Conditions

- location: everywhere in the model
- time: for the begin of the simulation period
- methods to specify initial conditions
 - > manual specification of local and global values
 - > steady state calculation
 - > result of another simulation: “hotstart”
- impact of initial conditions to results
- strategies to specify initial conditions



1D River Modelling

Simulation

- time: simulation period, time steps
- space: simulation grid points
- numerics: scheme parameter, iteration parameter, ...
stability criteria
implicit/explicit schemes -> solver type
- results: storage frequency,
type of physical state variables
location of physical state variables



Part 3

Theoretical Background Mike11



Mike11: Theoretical Background

Simulation Abstraction Steps

- **reality**
abstraction by physical system using assumptions, simplifications
- **physical system**
physical behavior described by physical laws and principles
- **physical laws**
described by differential equations
- **numerical method**
differential equations -> system of algebraic equations
- **mathematical algorithm**
solving the system of algebraic equations



Mike11: Theoretical Background

Reality

River Var



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Mike11: Theoretical Background

Physical System

- river network
- cross sections
- flood plains
- structures





Mike11: Theoretical Background

Physical Laws

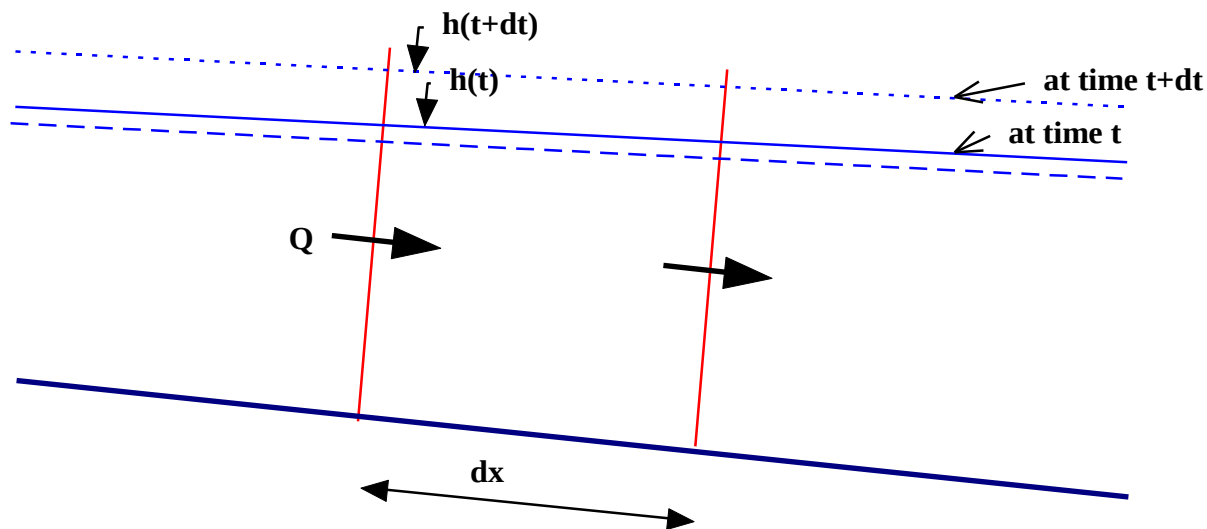
- 1D Saint-Venant Equations
 - simplification of the shallow water equations in 2D
 - depth-integrated Navier-Stokes equations
 - Continuity Equation** (Conservation of Mass)
 - Momentum Equation** (Conservation of Momentum)
- assumptions
 - incompressible and homogeneous fluid
 - flow is mainly one-dimensional
 - bottom slope is small
 - small longitudinal variation of cross-sectional parameters
 - hydrostatic pressure distribution



Mike11: Theoretical Background

Physical Laws - 1D Saint-Venant Equations

Continuity Equation (Conservation of Mass)



$$\rho \cdot Q \cdot dt - \rho \cdot \left(Q + \frac{\partial Q}{\partial x} dx \right) dt = \rho \cdot dA \cdot dx = \rho \cdot \frac{\partial A}{\partial t} dx \cdot dt \quad \frac{\partial Q}{\partial x} - B \cdot \frac{\partial h}{\partial t} = 0$$

increase of mass from t to Δt =

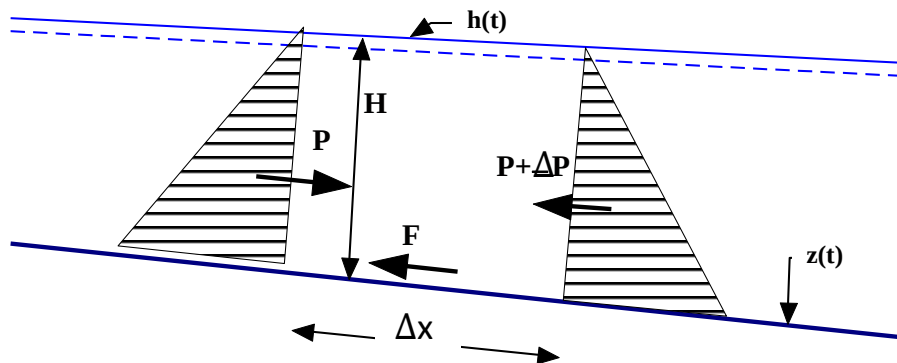
mass flux into control volume ($t \rightarrow t + \Delta t$) + mass flux out of control volume ($t \rightarrow t + \Delta t$)



Mike11: Theoretical Background

Physical Laws - 1D Saint-Venant Equations

Momentum Equation (Conservation of Momentum)



Momentum	= Mass per unit length * velocity
Momentum Flux	= Momentum * velocity
Pressure Force	= Hydrostatic Pressure P
Friction Force	= Force due to Bed Resistance
Gravity Force	= Contribution in X-direction

$$\frac{\Delta M}{\Delta t} = \frac{(M * U)}{\Delta x} + \frac{\Delta P}{\Delta x} - \frac{\Delta F_f}{\Delta x} + \frac{\Delta F_g}{\Delta x}$$

Momentum = Momentum Flux + Pressure - Friction + Gravity

increase of momentum $t \rightarrow t + \Delta t$ = momentum flux into control volume + sum of external forces

$$\frac{\partial Q}{\partial t} + \frac{\partial QV}{\partial x} + gA \frac{\partial H}{\partial x} + gA S_f + gA \frac{\partial z}{\partial x} = 0$$



Mike11: Theoretical Background

Physical Laws - 1D Saint-Venant Equations

Momentum Equation (Conservation of Momentum)

$$\frac{\partial Q}{\partial t} + \frac{\partial QV}{\partial x} + gA \left(\frac{\partial h}{\partial x} + S_f \right) = 0$$

$$v = \frac{1}{n} R^{\frac{2}{3}} S_f^{\frac{1}{2}}$$

Manning equation

$$C = \frac{1}{n} R^{\frac{1}{6}}$$

Chezy/Manning

$$S_f = \frac{Q|Q|n^2}{R^{\frac{4}{3}}A^2} = \frac{Q|Q|}{C^2R A^2}$$

-> rearranging for S_f

$$\frac{\partial Q}{\partial t} + \frac{\partial(Q\frac{Q}{A})}{\partial x} + gA \frac{\partial h}{\partial x} + g \frac{Q|Q|}{C^2R A} = 0$$

acceleration

local

convective

pressure

friction



Mike11: Theoretical Background

Physical Laws - 1D Saint-Venant Equations

- Continuity Equation (Conservation of Mass)

$$\frac{\partial Q}{\partial x} + \frac{\partial A}{\partial t} = q_l \quad q_l = \text{lateral inflow}$$

- Momentum Equation (Conservation of Momentum)

$$\frac{\partial Q}{\partial t} + \frac{\partial(Q \frac{Q}{A})}{\partial x} + gA \frac{\partial h}{\partial x} + g \frac{Q|Q|}{C^2 R A} = 0$$

- two partial differential equations
two unknowns - two coordinates

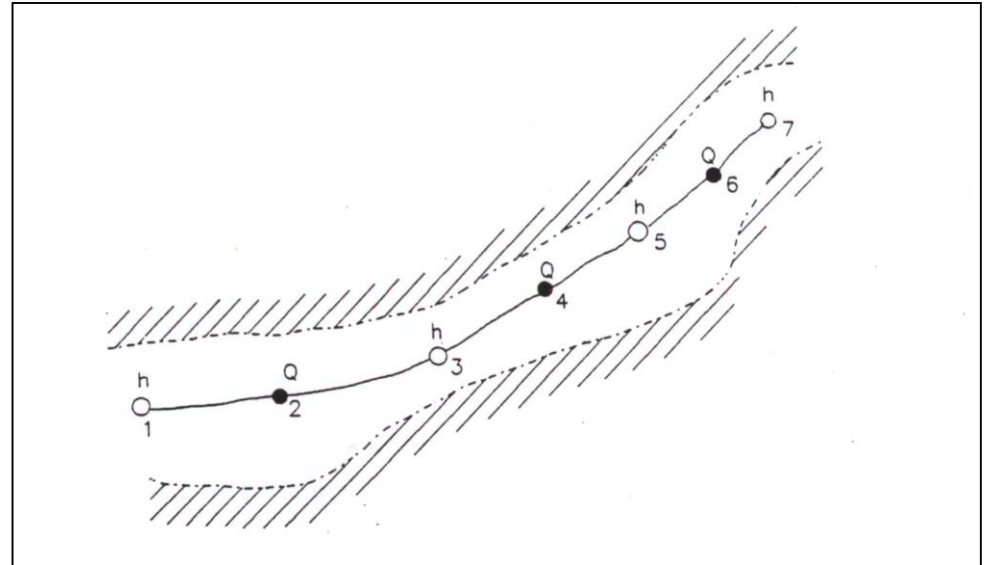


Mike11: Theoretical Background

Numerical Methods

- Finite Difference Method
implicit Abbott-Ionescu 6-point scheme
- two time levels
three space levels

staggered grid
alternate h , Q

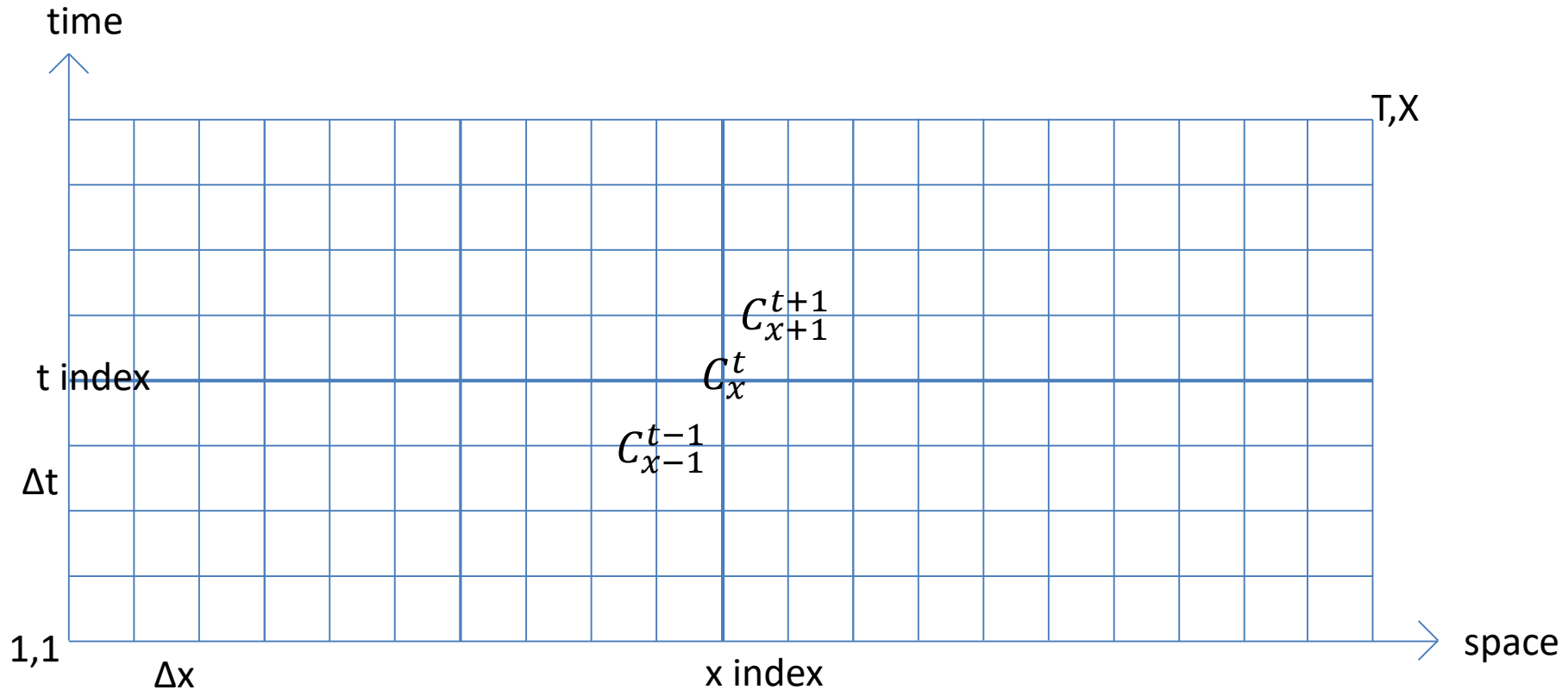




Mike11: Theoretical Background

Numerical Methods

Time and Space for one unknown variable C

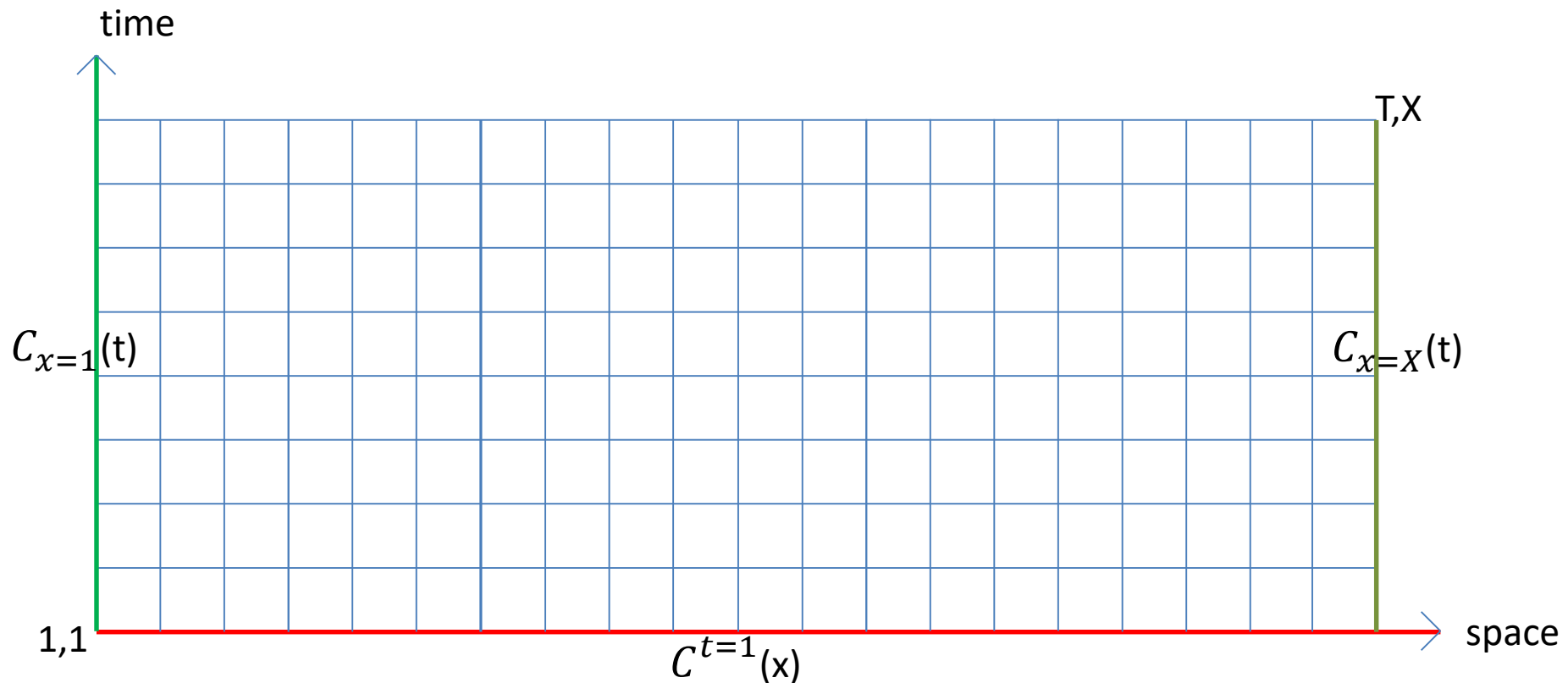




Mike11: Theoretical Background

Numerical Methods

Initial and Boundary Conditions





Mike11: Theoretical Background

Numerical Methods

Finite Difference Method

Discretisation in Time

$$\frac{\partial C}{\partial t} \Rightarrow \frac{C_x^{t+1} - C_x^t}{\Delta t}$$

forward difference in time

$$\frac{\partial C}{\partial t} \Rightarrow \frac{C_x^t - C_x^{t-1}}{\Delta t}$$

backward difference in time

$$\frac{\partial C}{\partial t} \Rightarrow \frac{C_x^{t+1} - C_x^{t-1}}{2 \Delta t}$$

central difference in time



Mike11: Theoretical Background

Numerical Methods

Finite Difference Method

Discretisation in Space

$$\frac{\partial C}{\partial x} \Rightarrow \frac{C_{x+1}^t - C_x^t}{\Delta x}$$

forward difference in space

$$\frac{\partial C}{\partial x} \Rightarrow \frac{C_x^t - C_{x-1}^t}{\Delta x}$$

backward difference in space

$$\frac{\partial C}{\partial x} \Rightarrow \frac{C_{x+1}^t - C_{x-1}^t}{2 \Delta x}$$

central difference in space



Mike11: Theoretical Background

Numerical Methods

Crank–Nicolson method

linear superposition of difference on old and new time level

superposition parameter $0 \leq \Theta \leq 1$

example central difference in space

$$\frac{\partial C}{\partial x} \Rightarrow \Theta \frac{C_{x+1}^{t+1} - C_{x-1}^{t+1}}{2\Delta x} + (1 - \Theta) \frac{C_{x+1}^t - C_{x-1}^t}{2\Delta x}$$

stability given for $\Theta \geq 0.5$ (Saint Venant equation)

in Mike11: $\Theta = 0.5$

$$\frac{\partial C}{\partial x} \Rightarrow 0.5 \frac{C_{x+1}^{t+1} - C_{x-1}^{t+1}}{2\Delta x} + 0.5 \frac{C_{x+1}^t - C_{x-1}^t}{2\Delta x} = \frac{\frac{C_{x+1}^{t+1} + C_{x+1}^t}{2} - \frac{C_{x-1}^{t+1} + C_{x-1}^t}{2}}{2\Delta x}$$



Mike11: Theoretical Background

Numerical Methods

Continuum Equation

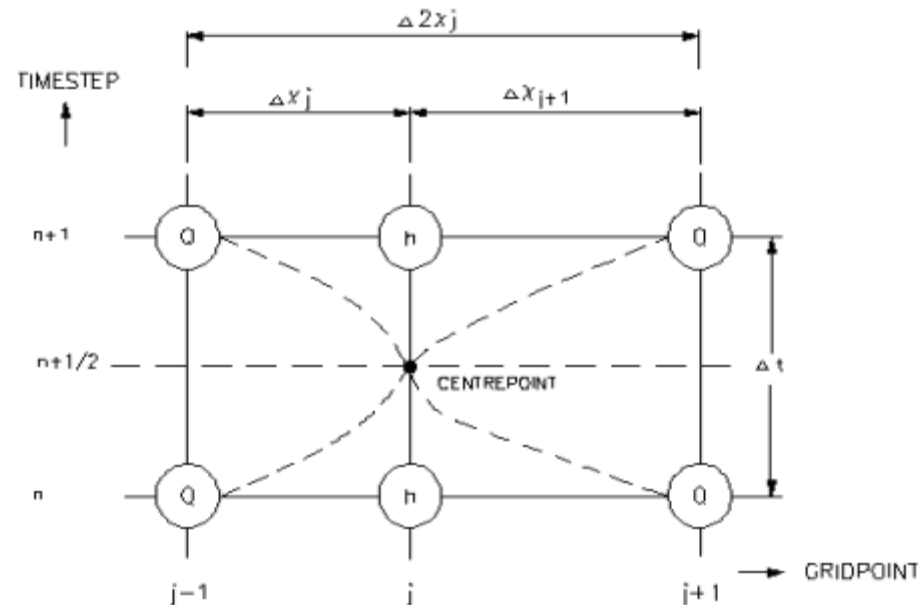
$$\frac{\partial Q}{\partial x} + \frac{\partial A}{\partial t} = q \quad \frac{\partial A}{\partial t} = b_s \frac{\partial h}{\partial t} \quad \frac{\partial Q}{\partial x} + b_s \frac{\partial h}{\partial t} = q$$

$$\frac{\partial Q}{\partial x} \approx \frac{\frac{(Q_{j+1}^{n+1} + Q_{j+1}^n)}{2} - \frac{(Q_{j-1}^{n+1} + Q_{j-1}^n)}{2}}{\Delta 2x_j}$$

$$\frac{\partial h}{\partial t} \approx \frac{(h_j^{n+1} - h_j^n)}{\Delta t}$$

$$b_s = \frac{A_{o,j} + A_{o,j+1}}{\Delta 2x_j}$$

$$\alpha_j Q_{j-1}^{n+1} + \beta_j h_j^{n+1} + \gamma_j Q_{j+1}^{n+1} = \delta_j$$





Mike11: Theoretical Background

Numerical Methods

Momentum Equation

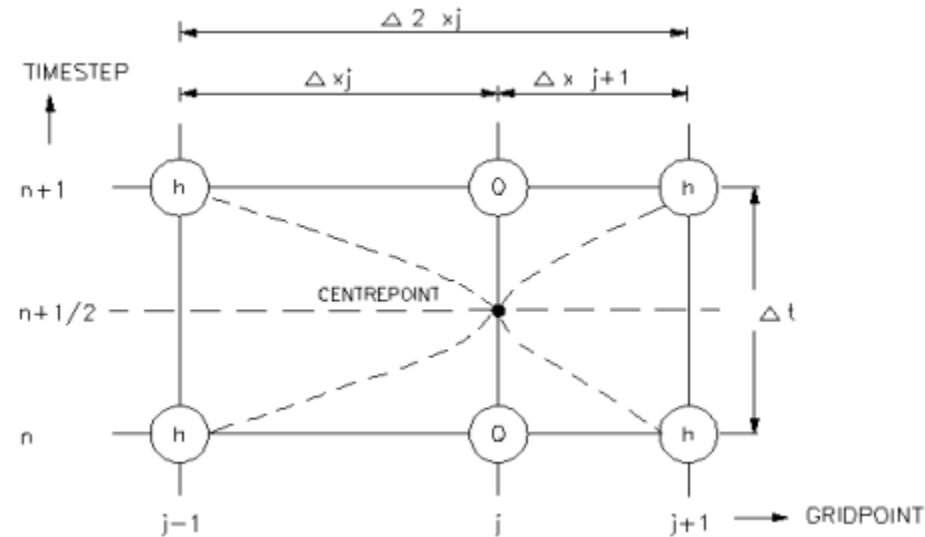
$$\frac{\partial Q}{\partial t} + \frac{\partial \left(\alpha \frac{Q^2}{A} \right)}{\partial x} + gA \frac{\partial h}{\partial x} + \frac{gQ|Q|}{C^2 AR} = 0$$

$$\frac{\partial Q}{\partial t} \approx \frac{Q_j^{n+1} - Q_j^n}{\Delta t}$$

$$\frac{\partial \left(\alpha \frac{Q^2}{A} \right)}{\partial x} \approx \frac{\left[\alpha \frac{Q^2}{A} \right]_{j+1}^{n+1/2} - \left[\alpha \frac{Q^2}{A} \right]_{j-1}^{n+1/2}}{\Delta 2x_j}$$

$$\frac{\partial h}{\partial x} \approx \frac{\frac{(h_{j+1}^{n+1} + h_{j+1}^n)}{2} - \frac{(h_{j-1}^{n+1} + h_{j-1}^n)}{2}}{\Delta 2x_j}$$

$$\alpha_j h_{j-1}^{n+1} + \beta_j Q_j^{n+1} + \gamma_j h_{j+1}^{n+1} = \delta_j$$



$$\alpha_j = f(A)$$

$$\beta_j = f(Q_j^n, \Delta t, \Delta x, C, A, R)$$

$$\gamma_j = f(A)$$

$$\delta_j = f(A, \Delta x, \Delta t, \alpha, q, v, \theta, h_{j-1}^n, Q_{j-1}^{n+1/2}, Q_j^n, h_{j+1}^n, Q_{j+1}^{n+1/2})$$



Mike11: Theoretical Background

Mathematical Algorithm

- equation system structure(one branch, no connection)

$$\alpha_j h_{j-1}^{n+1} + \beta_j Q_j^{n+1} + \gamma_j h_{j+1}^{n+1} = \delta_j$$

$$\alpha_j Q_{j-1}^{n+1} + \beta_j h_j^{n+1} + \gamma_j Q_{j+1}^{n+1} = \delta_j$$

$$\begin{bmatrix} \alpha_1 & \beta_1 & \gamma_1 & & & & & \delta_1 \\ & \alpha_2 & \beta_2 & \gamma_2 & & & & \delta_2 \\ & & \alpha_3 & \beta_3 & \gamma_3 & & & \delta_3 \\ & & & \alpha_4 & \beta_4 & \gamma_4 & & \delta_4 \\ & & & & \alpha_5 & \beta_5 & \gamma_5 & \delta_5 \\ & & & & & \cdot & \cdot & \cdot \\ & & & & & & \cdot & \cdot \\ & & & & & & & \alpha_{n-2} & \beta_{n-2} & \gamma_{n-2} & \delta_{n-2} \\ & & & & & & & & \alpha_{n-1} & \beta_{n-1} & \gamma_{n-1} & \delta_{n-1} \\ & & & & & & & & & \alpha_n & \beta_n & \gamma_n & \delta_n \end{bmatrix}$$



Mike11: Theoretical Background

Mathematical Algorithm

- equation system transformation

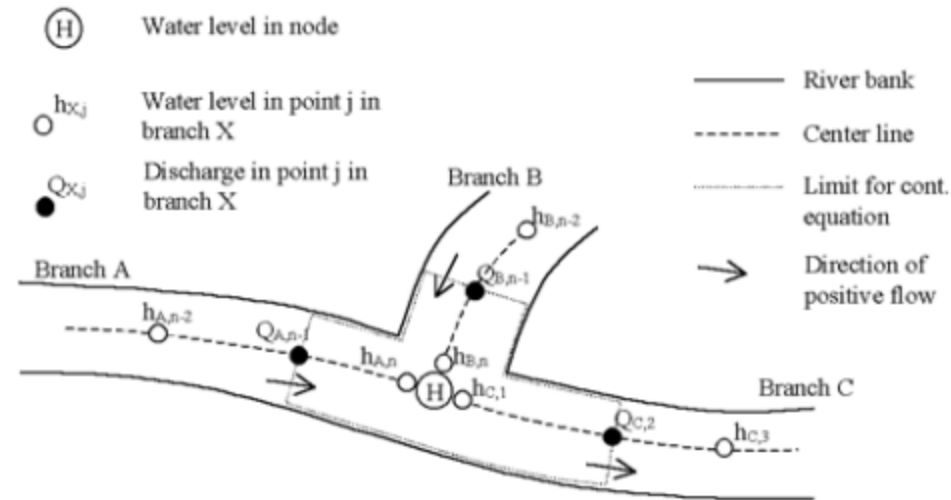
$$\begin{bmatrix}
 \alpha_1 & \beta_1 & \gamma_1 & & & & \delta_1 \\
 & \alpha_2 & \beta_2 & \gamma_2 & & & \delta_2 \\
 & & \alpha_3 & \beta_3 & \gamma_3 & & \delta_3 \\
 & & & \alpha_4 & \beta_4 & \gamma_4 & \delta_4 \\
 & & & & \alpha_5 & \beta_5 & \gamma_5 & \delta_5 \\
 & & & & & \ddots & \ddots & \ddots \\
 & & & & & & \ddots & \ddots \\
 & & & & & & & \alpha_{n-2} & \beta_{n-2} & \gamma_{n-2} & \delta_{n-2} \\
 & & & & & & & & \alpha_{n-1} & \beta_{n-1} & \gamma_{n-1} & \delta_{n-1} \\
 & & & & & & & & & \alpha_n & \beta_n & \gamma_n & \delta_n
 \end{bmatrix}
 \begin{bmatrix}
 a_1 & 1 & & & & & b_1 & c_1 \\
 a_2 & & 1 & & & & b_2 & c_2 \\
 a_3 & & & 1 & & & b_3 & c_3 \\
 a_4 & & & & 1 & & b_4 & c_4 \\
 a_5 & & & & & 1 & b_5 & c_5 \\
 \cdot & & & & & & \cdot & \cdot \\
 \cdot & & & & & & \cdot & \cdot \\
 a_{n-2} & & & & & & & 1 & b_{n-2} & c_{n-2} \\
 a_{n-1} & & & & & & & & 1 & b_{n-1} & c_{n-1} \\
 a_n & & & & & & & & & 1 & b_n & c_n
 \end{bmatrix}$$



Mike11: Theoretical Background

Mathematical Algorithm

- node point solution
-> branch network
- boundary equations
-> h known
-> Q known
-> Q/h relationship
- matrix bandwidth minimization
- Double Sweep algorithm





Part 4

MIKE11 Components



Mike11 Components

Mike11 File Structure (HD Simulation)

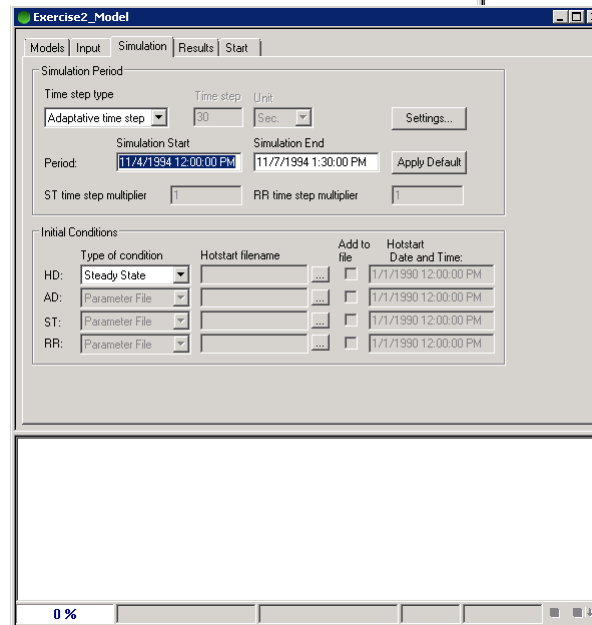
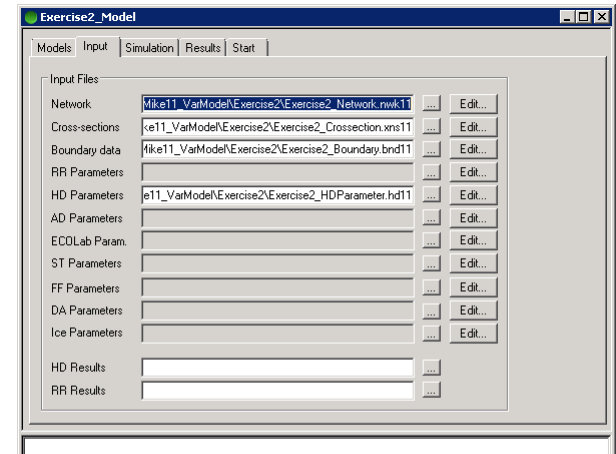
- Simulation File *.sim11 file
 - Network File *.nwk11 file
 - Crossection File *.xns11 file
 - Boundary File *.bnd11 file
 - Hydrodynamics Parameter File *.hd11 file
 - Time Series File *.dfs0 file
 - Result File *.res11 file (MikeView)
- > each file type do have a related editor tool within MikeZero
- > central core file is always the *.sim11 file (file to start modelling)



Mike11 Components

Simulation File

- simulation type/mode hydrodynamic/steady
- input files
- simulation data
 - time window
 - time step
 - initial conditions
- simulation results
 - result file, storage frequency
- simulation run control
 - warnings and errors





Mike11 Components

Network File

- river branch(s) geospatial location
 - branch name
 - topological id (e.g. year of measurement)
 - geospatial points (x-y system)
- control structure
 - examples: weirs
- grid points
 - generated points for numerical simulation
 - staggered grid for h and Q nodes (grid points)

	X Coord.	Y Coord.	Branch	Chainage Type	Chainage
1	990450	184280	Var	System Defined	0
2	990530	183620	Var	System Defined	664.83081
3	990470	183310	Var	System Defined	980.58387
4	990370	182740	Var	System Defined	1559.2893
5	990320	182410	Var	System Defined	1893.0557
6	990210	182030	Var	System Defined	2288.6565
7	990130	181460	Var	System Defined	2864.2432
8	990040	181160	Var	System Defined	3177.4524
9	989890	180650	Var	System Defined	3709.0537
10	989950	179950	Var	System Defined	4411.6204
11	990070	179570	Var	System Defined	4810.1176
12	990280	179230	Var	System Defined	5209.7425

	Name	Topo ID	Upstr. Ch.	Downstr. Ch.	Flow Direction	Maximum dx	Branch Type	Upstr. Conn. Name	Upstr. Conn. Ch.	Downstr. Conn. Name	Downstr. Conn. Ch.
1	Var	1994	0	24012.502	Positive	600	Regular				

	Chainage	Type	Data
✓	0.00	h	X-Sec
✓	236.80	Q	-
✓	473.60	h	-
✓	710.39	Q	-
✓	947.19	h	-
✓	1183.99	Q	-
✓	1420.79	h	-
✓	1657.58	Q	-
✓	1894.38	h	X-Sec
✓	2154.94	Q	-

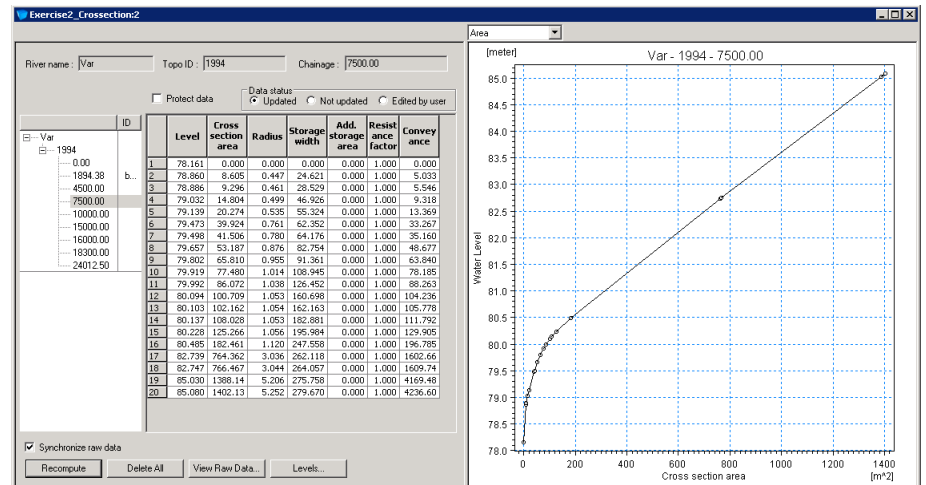
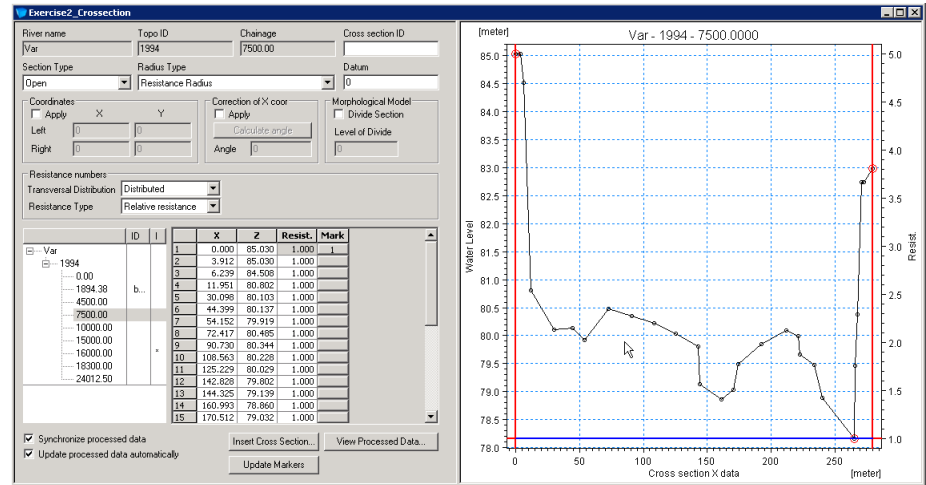
	Q	H-Pos	H-Neg	H-Weir	Width	Area
1	0	33	33	33	100	0
2	157.209	33.9675	34.0756	33.6316	100	63.158
3	444.654	34.8931	35.1095	34.2632	100	126.316
4	816.882	35.8128	36.1196	34.8947	100	189.474
5	1257.67	36.7312	37.1363	35.5263	100	252.632
6	1757.65	37.6499	38.1949	36.1579	100	315.79
7	2310.49	38.5662	39.2601	36.7895	100	378.948
8	2911.55	39.518	40.3239	37.4211	100	442.106



Mike11 Components

Crossection File

- crossection location
 - branch name
 - chainage
 - topological id (e.g. year of measurement)
- crossection points
 - profile coordinate (x)
 - vertical elevation (z)
- marker
 - examples:
 - left levee bank
 - lowest point (bed)
 - right levee bank
- processed data
 - e.g. A/h relationship





Mike11 Components

Boundary File

- boundary condition
 - type of boundary condition
 - branch name
 - chainage
- boundary condition values
 - constant value
 - time series item

Exercise2_Boundary

	Boundary Description	Boundary Type	Branch Name	Chainage	Chainage	Gate ID	Boundary ID
1	Open	Inflow	Var	0	0		
2	Open	Water Level	Var	24012.5026	0		

☒ Include HD calculation
☐ Include AD boundaries

	Data Type	TS Type	File / Value	TS Info
1	Discharge:	TS File	Exercise2_TimeSeries ... Edit	Q



Mike11 Components

Time Series File

- type of time series
 - equidistant, non-equidistant
 - start time, time step, number of time steps
- items
 - item name
 - type of value, unit

File Properties

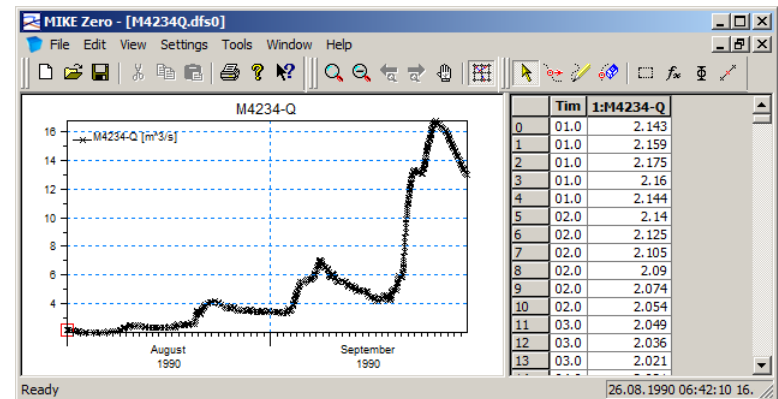
General Information
Title: M4234-Q

Axis Information
Axis Type: Non-Equidistant Calendar Axis
Start Time: 01.08.1990 00:00:00
Time Step: 0 [days]
00:00:10 [hour:min:sec]
0.000 [fraction of sec.]
No. of Timesteps: 722
Axis Units:

Item Information

	Name	Type	Unit	
1	M4234-Q	Discharge	m ³ /s	Instant

Insert Append Delete Item Filtering...





Mike11 Components

Hydrodynamic Parameter

- Bed Resistance
 - global or branch oriented
 - Manning (m), Strickler (M) or Chezy (C)
- Additional Output examples:
 - velocity
 - Froude number
 - mass error
- several other options/parameters
 - ...

Exercise2_HDPParameter

Reach Lengths | Add. Output | Flood Plain Resist. | User Def. Marks | Encroachment
Heat Balance | Stratification | Time Series Output | Maps | Groundwater Leakage
Initial | Wind | Bed Resist. | Bed Resist. Toolbox | Wave Approx | Default Values | Quasi Steady

Approach
☒ Uniform Section
☐ Tripple zone

Resistance Formula
Manning (M)

Global Values
Resistance Number: 30

Local Values

	River Name	Chainage	Resistance
1			30

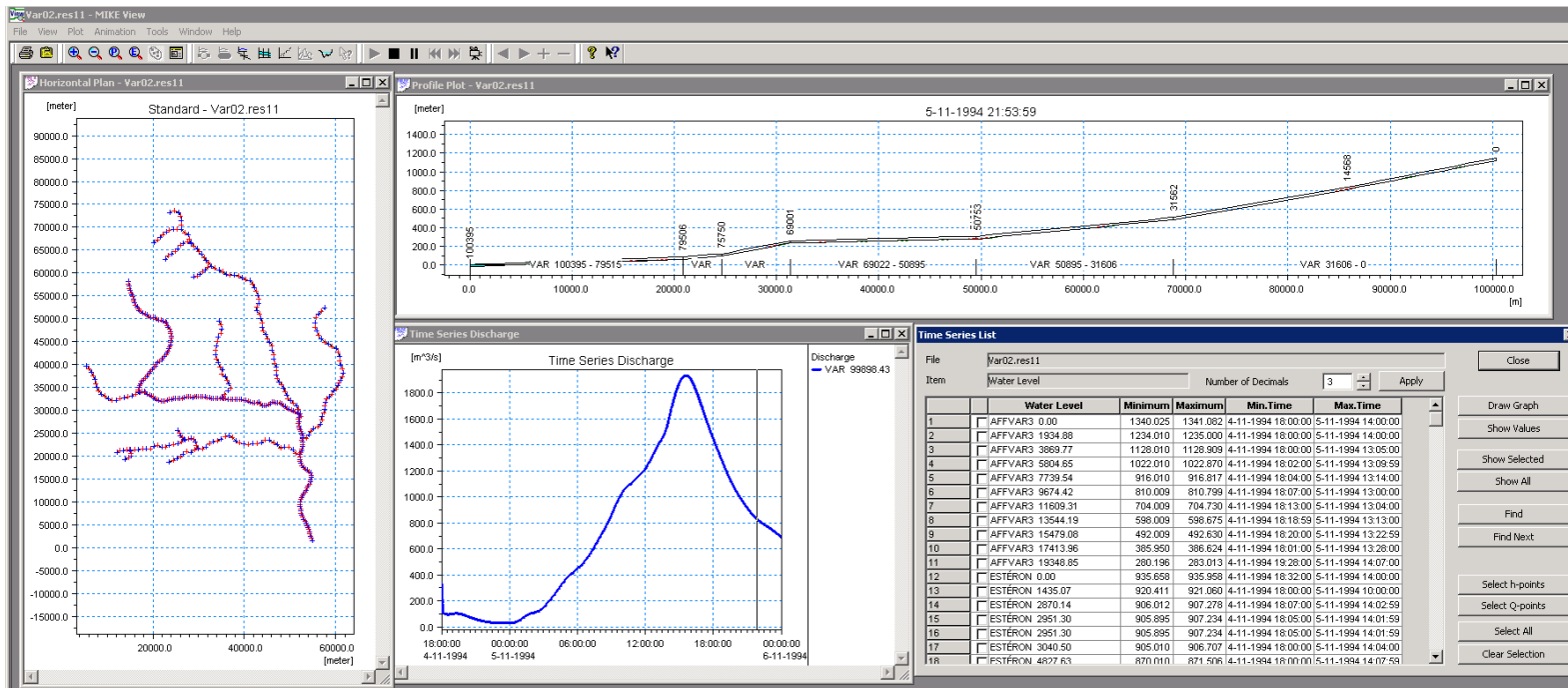


Mike11 Components

Result File

The results are stored in a file with the suffix *res11*.

MikeView is used to visualize and analyse the results of Mike11.





Part 5

MIKE11 Exercises



Mike11 Exercise

Exercise 1: Simple Academic Test Case

Set-up of a new model (see tutorial)

- straight channel
 - 5 km length
 - cross section width = 50 m, height = 10 m
 - slope: 0%
 - material: concrete
- initial condition
 - horizontal water level 4 m, discharge 0 m/s
- boundary condition:
 - upstream: water level time series 4 m with 6m peak
 - downstream: discharge = 0 m³/s (wall)



Mike11 Exercise

Exercise 2: Simplified River Model Case Study

Running a given model (see tutorial)

- given Mike11 model files:

network	Exercise2_Network.nwk11
cross sections	Exercise2_Crosssection.xns11
parameter file	Exercise2_HDPParameters.hd11
boundary conditions	Exercise2_Boundary.bnd11
	Exercise2_TimeSeries.dfs0
simulation model	Exercise2_Model.sim11
- boundary conditions
 - upstream:

discharge time series
1) $Q = 300 \text{ m}^3/\text{s}$
2) Q with synthetic flood peak wave
 - downstream:

water level $h = 0$ (sea level)

- initial conditions

steady state calculation

- roughness

Strickler value of 30



Mike11 Exercise

Exercise 2: Simplified River Var Model Case Study

Simulation Task

- analyse the given river model for normal flow condition
- analyse the given river model for the 1994 flood event
- analyse the impact of the roughness parameter
- analyse the impact of a weir